

## APPENDIX A

### THEORETICAL BACKGROUND CONCERNING THE RAMAN MEASUREMENTS OF $\langle P_2 \rangle$ AND $\langle P_4 \rangle$ .<sup>1</sup>

#### A. Orientational statistics and microscopic order parameters

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We assume the molecules to be rigid but of arbitrary shape and consider two coordinate systems: (i) the laboratory frame ( $x, y, z$ ) fixed with respect to the liquid crystal medium with the  $z$  axis parallel to the director  $\hat{n}$ , and (ii) the molecular frame (1,2,3) fixed to the molecule. The 3 axis is chosen to be parallel to the major molecular axis.

At any instant the orientation of a particular molecule is described by the three Euler angles ( $\alpha, \beta, \gamma$ ) linking the two coordinate systems.<sup>2</sup> The orientational order of the molecules can then be described by a distribution function  $f(\alpha, \beta, \gamma)$  which can be expanded in terms of the generalized spherical harmonics, the

Wigner matrices<sup>3</sup>  $D_{m,m}^{(L)}(\alpha, \beta, \gamma)$ :

$$f(\alpha, \beta, \gamma) = \sum_{L=0}^{\infty} \sum_{m=-L}^L \frac{2L+1}{8\pi^2} a_{m,m}^{(L)} D_{m,m}^{(L)}(\alpha, \beta, \gamma) \quad .. (1)$$

with

$$a_{m,m}^{(L)} = \int_0^{2\pi} d\alpha \int_0^\pi \sin\phi d\phi \int_0^{2\pi} d\gamma D_{m,m}^{(L)*}(\alpha, \beta, \gamma) f(\alpha, \beta, \gamma) \\ = \langle D_{m,m}^{(L)*}(\alpha, \beta, \gamma) \rangle,$$

where  $\langle \dots \rangle$  represents a statistical average.

The coefficients  $a_{m,m}^{(L)}$  with non-zero L depend on the degree of orientational ordering. They are temperature dependent and saturate to constant values if the system becomes completely \_\_\_\_\_. They therefore be chosen as a set of generalised orientational order parameters characterising the degree of ordering. It can be shown that for each L there are  $(2L + 1)^2$

independent real orientational order parameters.

Considering a uniaxial macroscopic system with the unique axis parallel to the  $\hat{z}$  axis, the distribution function is independent of  $\alpha$  and only terms with  $m' = 0$  contribute to the summation. The physical equivalence of  $\hat{n}$  and  $-\hat{n}$  leaves only terms with even  $L$ . We then have

$$f(\alpha, \beta, \gamma) = \sum_{L \text{ even}} \sum_{m=-L}^{L+1} \frac{2L+1}{8\pi^2} a_m^{(L)} D_m^{(L)}(\alpha, \beta, \gamma) \dots (2)$$

where

$$D_m^{(L)}(\alpha, \beta, \gamma) = \left(\frac{4\pi}{2L+1}\right)^{1/2} (-1)^m Y_m^{2L+1}(\beta, \gamma).$$

Thus we have  $(2L+1)$  real, independent order parameters for each (even)  $L$ . For the case  $L = 2$  we have five nontrivial order parameters.

Equation (2) can be written explicitly<sup>4</sup> employing the real quantities  $A_m^{(L)}$  and  $B_m^{(L)}$  given by

Лінійна залежність виразу від  $x$  виконується тоді, якщо

$$\cdot (d \cos)^{\frac{1}{2}} d \left[ \frac{x^2}{4} / (1 + x^2) \right] = (1 + x)^{\frac{1}{2}} x$$

тобто  $\frac{d}{dx} \left( \frac{x^2}{4} / (1 + x^2) \right)$  має вигляд  $(1 + x)^{-\frac{1}{2}}$ . Це відповідає умові  $\frac{d}{dx} \left( \frac{x^2}{4} / (1 + x^2) \right) = \frac{1}{2} x (1 + x)^{-\frac{3}{2}}$ .

$\cdot (1 + x)^{\frac{1}{2}}$  є розв'язок рівняння

з викладанням відповідно до змінної  $x$ . Але саме це викладання відповідає рівнянню  $\frac{dy}{dx} = \frac{y}{x}$ , тобто  $y = Cx$ , де  $C$  - константа.

Із цього випливає, що  $(1 + x)^{\frac{1}{2}}$  є розв'язком рівняння  $\frac{dy}{dx} = y$ .

• рівняння  $\frac{dy}{dx} = y$  має відомий розв'язок  $y = Cx$ , тобто  $y = Cx$  є розв'язком рівняння  $\frac{dy}{dx} = y$ . Але  $y = Cx$  є розв'язком рівняння  $\frac{dy}{dx} = y$  тоді і тільки тоді, коли  $C \neq 0$ .

$$\cdot (T)^{\frac{1}{2}T} + (T)^{\frac{1}{2}} = \frac{1}{2}(T)^{\frac{1}{2}} = (T)^{\frac{1}{2}}$$

symmetric rods, one obtains

$$f(\alpha, \beta, \gamma) = \sum_{L \text{ even}} \frac{2L+1}{8\pi^2} A_e^{(L)} P_L(\cos \beta) \quad (3)$$

or

$$\begin{aligned} f_{\hat{u}}(\beta) &= \int_0^{2\pi} d\alpha \int_0^{2\pi} d\gamma f(\alpha, \beta, \gamma) \\ &= \sum_{L \text{ even}} \frac{2L+1}{2} A_e^{(L)} P_L(\cos \beta) \end{aligned} \quad (4)$$

and

$$\begin{aligned} A_e^{(L)} &= \int_0^{\pi} \sin \beta \, d\beta \, P_L(\cos \beta) \, f_{\hat{u}}(\beta) \\ &= \langle P_L(\cos \beta) \rangle \end{aligned} \quad (5)$$

where  $\hat{u}$  is the unit vector along the symmetry axis of the molecule.

The order parameters  $A_e^{(L)}$  is 0 in the isotropic phase,  $\pm 1$  in the completely ordered phase and should take values lying between 0 and 1 in the liquid crystalline phase.

### B. Orientational Order by Raman Scattering

The power spectrum of the Raman scattered light can be expressed as a fourth rank tensor which is related to the average orientational correlation function of the molecular Raman polarisability. This suggests that application of Raman scattering to the anisotropic liquid crystalline system will yield not only the order parameters with  $L = 2$  but also parameters of the next higher order, i.e., terms with  $L = 4$ .<sup>5</sup>

Consider a single Raman active vibrational mode with normal coordinate  $Q$  and frequency  $\omega$ . We introduce a Raman polarisability tensor  $\alpha'$ , whose time dependence in a reference frame fixed with respect to the molecule follows that of  $Q$ .

$$\alpha' = \left( \frac{\partial \alpha}{\partial Q} \right)_{Q=0} Q \quad (6)$$

If  $\alpha'$  is interpreted as a microscopic property of the individual molecule one should, in principle,

apply local field corrections to connect the macroscopic properties to the microscopic ones. However, several empirical evidences<sup>6,7</sup> suggest that these are not significant here. Thus  $\alpha'$  in equation (6) can be treated as a molecular polarisability which is essentially unchanged in the molecular frame when the material changes from the isotropic to any liquid crystalline phase.

Lax and Nelson<sup>8</sup> have developed theoretical expressions relating the observed ratios of integrated intensities (depolarization ratios) for a particular Raman band to the statistical averages of the Raman polarisability tensors  $\alpha'_L$  as expressed in the laboratory frame, taking into account solid angle changes and transmission losses at the sample surfaces. For the geometries employed in our experiments (see figure 6.2, chapter 6) these results are

$$\begin{aligned}
 R_1 &= q_n \frac{\langle (\alpha_L')_{yz}^2 \rangle}{\langle (\alpha_L')_{zz}^2 \rangle} \\
 R_2 &= \frac{\langle (\alpha_L')_{xy}^2 \rangle}{q_n \langle (\alpha_L')_{yy}^2 \rangle} \\
 R_3 &= \frac{\langle (\alpha_L')_{yx}^2 \rangle}{\langle (\alpha_L')_{xx}^2 \rangle}
 \end{aligned} \quad (7)$$

where the correction factor  $q_n = \frac{(n_g + n_o)^2}{(n_g - n_o)^2}$ .

The Raman tensor for a particular Raman active vibration will have some form  $\alpha'_n$  in the molecular frame of reference. However, there is always some other molecular axis, related to this one, in which the Raman tensor has the diagonal form

$$\alpha'_d = \alpha \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (8)$$

The components of  $\alpha'_L$  in the molecular frame can be expressed in terms of  $a, b$  and the three Eulerian angles  $\alpha_0, \beta_0$  and  $\gamma_0$  that bring the principal axis of  $\alpha'_L$  (i.e., the axis for which  $\alpha$  has the diagonal form) into coincidence with the special symmetry axis of the molecule.

For a system with macroscopic uniaxial symmetry, there are only four independent orientational averages in terms of which the three ratios (equation 7) can be rewritten as

$$\begin{aligned}
 R_1 &= a_L \frac{\langle (\alpha'_L)_{xz}^2 \rangle}{\langle (\alpha'_L)_{zz}^2 \rangle} , \\
 R_2 &= \frac{\langle (\alpha'_L)_{xz}^2 \rangle}{a_L \langle (\alpha'_L)_{xx}^2 \rangle} . \quad (9) \\
 R_3 &= \frac{\langle (\alpha'_L)_{xy}^2 \rangle}{\langle (\alpha'_L)_{xx}^2 \rangle}
 \end{aligned}$$

These ratios can be expressed in terms of the microscopic molecular quantities  $a$  and  $b$ , the Eulerian angles ( $\alpha_0, \beta_0, \gamma_0$ ), and the orientational order parameters corresponding to  $L = 2, 4$ .

In the special case of cylindrical symmetry about the 3-axis one obtains<sup>9</sup>

$$\begin{aligned} A^{-2} \langle (a_L^1)_{xx}^2 \rangle &= \frac{1}{9} + \frac{3}{16}B + \frac{1}{4}C + \frac{1}{16}D + \frac{11}{288}D^2 \\ &+ \left( \frac{1}{16}B + \frac{1}{4}C - \frac{1}{6}D - \frac{3}{48}D^2 \right) \langle \cos^2 \beta \rangle \\ &+ \left( \frac{3}{16}B - \frac{1}{4}C + \frac{3}{32}D^2 \right) \langle \cos^4 \beta \rangle , \end{aligned}$$

$$\begin{aligned} A^{-2} \langle (a_L^1)_{xy}^2 \rangle &= \frac{1}{16}B + \frac{1}{4}C + \frac{1}{32}D^2 + \left( \frac{3}{16}B - \frac{1}{16}D^2 \right) \langle \cos^2 \beta \rangle \\ &+ \left( \frac{1}{16}B - \frac{1}{4}C + \frac{1}{32}D^2 \right) \langle \cos^4 \beta \rangle , \end{aligned}$$

$$\begin{aligned} A^{-2} \langle (a_L^1)_{zz}^2 \rangle &= \frac{1}{4}B + \frac{1}{4}C - \left( \frac{3}{4}C - \frac{1}{8}D^2 \right) \langle \cos^2 \beta \rangle \\ &- \left( \frac{1}{8}B - 0 + \frac{1}{8}D^2 \right) \langle \cos^4 \beta \rangle , \end{aligned}$$

$$\begin{aligned}
 A^{-2} \langle (a_L')_{xx}^2 \rangle &= \frac{1}{3} + \frac{1}{2}B - \frac{1}{3}D + \frac{1}{3}B^2 \\
 &- (B - 2C - \frac{1}{3}D + \frac{1}{6}D^2) \langle \cos^2 \beta \rangle \\
 &+ (\frac{1}{2}B - 2C + \frac{1}{4}D^2) \langle \cos^4 \beta \rangle, \quad (10)
 \end{aligned}$$

where

$$\begin{aligned}
 A &= a_{11}' + a_{22}' + a_{33}' \\
 B &= (1/A^2)[\frac{1}{4}(a_{11}' - a_{22}')^2 + a_{12}'^2] \\
 C &= (1/A^2)(a_{13}'^2 + a_{23}'^2) \\
 D &= (1/A)(2a_{33}' - a_{11}' - a_{22}')
 \end{aligned}$$

At any particular temperature the three ratios in equation (9) give three equations linear in the two unknowns  $\langle \cos^2 \beta \rangle$  and  $\langle \cos^4 \beta \rangle$  with three parameters B, C and D. In addition, the depolarisation ratio in the isotropic phase gives another relation between these three parameters,

$$R_{iso} = \frac{3}{4} \left( \frac{12B + 12C + D^2}{5 + 12B + 12C + D^2} \right) \quad (11)$$

It is then possible to solve from the data for the two order parameters

$$A_0^{(2)} = \frac{1}{2} \langle 3\cos^2 \beta - 1 \rangle ,$$

and

$$A_0^{(4)} = \frac{1}{8} \langle 35\cos^4 \beta - 30\cos^2 \beta + 3 \rangle . \quad (12)$$

References

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- 3 W.E. Rose, Elementary Theory of Angular Momentum (Wiley, New York, 1957).
- 4 See page 4637 of Ref. 1 above.
- 5 E.B. Priestley, P.S. Pershan, R.B. Meyer and D.H. Dolphin, *Raman Rev.* Vol. Vijnana Parishad Annaandhan Patrika **14**, 93 (1971).
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 (b) M. Lax and D.F. Nelson, *Proc. Third Rochester Conf. on Coherent and Quantum Optics*, edited by L.Mandel and H.Wolf (Plenum, New York, 1973).
- 9 See page 4640 of Ref. 1 above.

## APPENDIX B

### PROCEDURE AND PROGRAM USED TO CALCULATE $\langle P_2 \rangle$ AND $\langle P_4 \rangle$ FROM RAMAN DEPOLARIZATION RATIOS

#### A. Procedure

In a frame of reference fixed to the molecule, a particular Raman polarisability tensor can be written in the diagonal form given in equation (8) of Appendix A. From the symmetry of the 7CB and 8 COB molecules employed in the studies described in chapter 6, it is reasonable to assume that the molecular axis coincides with one of the axes in the Raman tensor. We take this to be the  $z$  axis.

Assuming that the molecular polarisability is not uniaxial ( $a \neq b$ ), the parameters  $A$ ,  $B$ ,  $C$  and  $D$  in equations (10) of Appendix A reduce to

$$\begin{aligned}A &= 1 + a + b \\B &= (a - b)^2 / 4a^2 \\C &= 0 \\D &= (2 - a - b)/\Delta\end{aligned}\tag{1}$$

Also,

$$\frac{R_{iso}}{R_{iso}} = \frac{3(a^2 + b^2 + 1 - a - b - ab)}{5(a + b + 1)^2 + 4(a^2 + b^2 + 1 - a - b - ab)} \dots (2)$$

Starting with an arbitrary value of  $b$  ( $0 < b < 1$ )  $a$  is determined from equation (2) and hence the parameters  $A$ ,  $B$  and  $D$  in equation (1).

Combining equations (10) with equations (9) of Appendix A we obtain,

$$\begin{aligned} & \left[ \frac{1}{8}B^2 + \frac{R_1}{Q_B}(B - \frac{1}{3}D + \frac{1}{3}B^2) \right] \langle \cos^2 \theta \rangle \\ & - \left[ (\frac{1}{2}B + \frac{1}{3}B^2)(\frac{R_1}{Q_B} + \frac{1}{2}) \right] \langle \cos^4 \theta \rangle \\ & = \frac{R_1}{Q_B}(\frac{1}{3}B + \frac{1}{3}B^2 - \frac{1}{3}D + \frac{1}{3}B^2) - \frac{1}{3}D \end{aligned} \quad (3)$$

and

$$\begin{aligned} & \left[ R_2 C_B \left( \frac{1}{8}B - \frac{1}{3}D - \frac{5}{48}B^2 \right) - \frac{1}{3}B^2 \right] \langle \cos^2 \theta \rangle \\ & + \left[ \frac{3}{16}R_2 C_B \left( B + \frac{1}{2}B^2 \right) + \frac{1}{4}(B + \frac{1}{2}B^2) \right] \langle \cos^4 \theta \rangle \\ & = \frac{1}{4}B - R_2 C_B \left( \frac{1}{3} + \frac{3}{16}B + \frac{1}{16}D + \frac{11}{288}B^2 \right) \end{aligned} \quad (4)$$

Here  $\theta$  replaces  $\beta$  employed in Appendix A. (3) and (4)

give two linear equations in the two unknowns  $\langle \cos^2 \theta \rangle$  and  $\langle \cos^4 \theta \rangle$ . We solve for them and impose the condition  $\frac{1}{3} \langle \cos^2 \theta \rangle < 1$  which is a physical requirement.

We now compute

$$R_3(\text{cal}) = \frac{\frac{1}{2}(B - \frac{1}{2}D^2) \langle \cos^2 \theta \rangle + \frac{1}{16}(B + \frac{1}{2}D^2)(\langle \cos^4 \theta \rangle + 1)}{\left[ \frac{1}{2} + \frac{3}{16}B + \frac{1}{16}D + \frac{11}{256}D^2 + (\frac{1}{8}B - \frac{1}{8}D - \frac{5}{48}D^2) \langle \cos^2 \theta \rangle + \frac{3}{16}(B + \frac{1}{2}D^2) \langle \cos^4 \theta \rangle \right]} \dots (5)$$

and compare the result with the experimental value of  $R_3$ .

If  $|R_3(\text{cal}) - R_3(\text{expt})| \geq 0.01$  we ignore the results, go back to equation (2) and repeat the series of calculations with an incremented value  $b + \Delta b$ . The procedure is repeated till  $|R_3(\text{cal}) - R_3(\text{expt})| < 0.01$ . Now the incremental value  $\Delta b$  is reduced to  $\Delta b/10$  and the calculations repeated till we obtain  $|R_3(\text{cal}) - R_3(\text{expt})| \leq 0.001$ . We accept the value of  $b$  (and hence the corresponding values of  $a$ ,  $A$ ,  $B$  and  $D$ ) which satisfies this requirement and then solve for  $\langle \cos^2 \theta \rangle$  and  $\langle \cos^4 \theta \rangle$ . Finally, we compute the order parameters given by

$$\langle P_2(\cos \theta) \rangle = \frac{1}{2}[3 \langle \cos^2 \theta \rangle - 1] \quad (6)$$

and

$$\langle P_4(\cos \theta) \rangle = \frac{1}{3} [35 \langle \cos^4 \theta \rangle - 30 \langle \cos^2 \theta \rangle + 3] \quad (7)$$

### B. Computation Program

$\langle P_2(\cos \theta) \rangle$  and  $\langle P_4(\cos \theta) \rangle$  values were calculated from the experimentally determined Raman depolarisation ratios  $R_1$ ,  $R_2$ ,  $R_3$  and  $R_{iso}$  and the correction factor  $C_R$ , employing the above iterative procedure, on a Hewlett-Packard Model 9821A programmable desk-top calculator. The following program was employed.

0 :

ENTER 2/.50X, "COMPUTATION OF ORDER PARAMETERS P<sub>2</sub> AND P<sub>4</sub> FROM"; TYP |

1 :

ENTER /.40X, "RAMAN DEPOLARISATION RATIOS"; TYP |

2 :

ENTER 3/.5X, "COMPOUND", 6X, "PHASE", 6X, "TEMPERATURE", TYP |

3 :

ENTER 4/.5X, "DA", 8X, "DB", 8X, "A", 8X, "B", 9X, "D", 5X, "COS(B)/2", 5X, 2; TYP |

4 :

**INT "COS(B)MM4", SX, "R3(CAL)", SX, "P(2)", SX,  
"P(4)", /, TIP** ⊢

5 :

**INT "NOT", R16, "R(I80)?", R9** ⊢

6 :

"READY", 0 → R19; **INT "NOT", R17, "NOT", R18** ⊢

7 :

**(R16 + R17)/(R16 + R18) → R3; R3R3 → R3** ⊢

8 :

**INT "R1?", R1, "R2?", R2, "R3(EXPT)?", R4** ⊢

9 :

**INT "B(MIN) ?", R10, "B(MAX) ?", R11** ⊢

10 :

**INT "DELTA B?", R12** ⊢

11 :

"INCREMENT", IF (ABS(X-R4) ≤ .01)(R19=1); **R12/10 → R12** ⊢

12 :

 $R10 \leftarrow R12 \rightarrow R10 \vdash$ 

13 :

IF  $R10 > R11$ , 050 "END"  $\vdash$ 

14 :

 $36(3R5-1)(R5(3R10 \uparrow 2 + 2R10+3) - (R10 \uparrow 2 - R10+1)) \rightarrow Z \vdash$ 

15 :

 $\sqrt{((3(R10+1)(2R5+1)) \uparrow 2 - Z)} \rightarrow R15 \vdash$ 

16 :

 $(-3(R10 + 1)(2R5 + 1) + R15)/6(3R5 - 1) \rightarrow R20 \vdash$ 

17 :

 $(-3(R10+1)(2R5+1) - R15)/6(3R5 - 1) \rightarrow R30 \vdash$ 

18 :

"START", 1 + R20 + R10  $\rightarrow$  R40; 1 + R30 + R10  $\rightarrow$  R45  $\vdash$ 

19 :

 $(R20 - R10) \uparrow 2/4R40 \uparrow 2 \rightarrow R50; (R30 - R10) \uparrow 2/4R45 \uparrow 2 \rightarrow R55 \vdash$

20 :

$$(2 - R_{20} - R_{10})/R_{40} \rightarrow R_{60}; \quad (2 - R_{50} - R_{10})/R_{45} \rightarrow R_{65} \vdash$$

21 :

$$1/8mR_{60} \uparrow 2 + R_1/R_{3m}(R_{50} - 1/2mR_{60} + 1/6mR_{60} \uparrow 2) \rightarrow R_{70} \vdash$$

22 :

$$1/8mR_{65} \uparrow 2 + R_1/R_{3m}(R_{55} - 1/2mR_{65} + 1/6mR_{65} \uparrow 2) \rightarrow R_{80} \vdash$$

23 :

$$-(.5R_{50} + .25R_{60} \uparrow 2)(R_1/R_3 + .5) \rightarrow R_{90} \vdash$$

24 :

$$-(.5R_{55} + .25R_{65} \uparrow 2)(R_1/R_3 + .5) \rightarrow R_{100} \vdash$$

25 :

$$R_1/R_{3m}(.5R_{50} + 1/36mR_{60} \uparrow 2 + 1/9m(1 - R_{60})) - .25R_{50} \rightarrow R_{110} \vdash$$

26 :

$$R_1/R_{3m}(.5R_{55} + 1/36mR_{65} \uparrow 2 + 1/9m(1 - R_{65})) - .25R_{55} \rightarrow R_{120} \vdash$$

27 :

$$R_2/R_3(1/8mR_{50} - 1/6mR_{60} - 5/48mR_{60} \uparrow 2) - 1/8mR_{60} \uparrow 2 \rightarrow R_{130} \vdash$$

28 :

$$R2R3(1/R2R55 - 1/R2R65 - 5/R2R65 \uparrow 2) - 1/R2R65 \uparrow 2 \rightarrow R140 \vdash$$

29 :

$$.25(R50 + .5R60 \uparrow 2)(1 + .75R2R3) \rightarrow R150 \vdash$$

30 :

$$.25(R55 + .5R65 \uparrow 2)(1 + .75R2R3) \rightarrow R160 \vdash$$

31 :

$$.25R50 - R2R3(1/9 + 3R50/16 + R60/16 + 11R60 \uparrow 2/288) \rightarrow R170 \vdash$$

32 :

$$.25R55 - R2R3(1/9 + 3R55/16 + R65/16 + 11R65 \uparrow 2/288) \rightarrow R180 \vdash$$

33 :

$$(R150R110 - R90R170)/(R70R150 - R130R90) \rightarrow I \rightarrow R200 \vdash$$

34 :

$$IF (1/3 \leq x) (x \leq 1), R20 \rightarrow R190; R70 \rightarrow R210; R90 \rightarrow R220; \\ R110 \rightarrow R230; R130 \rightarrow R240 \vdash$$

35 :

$$IF (1/3 \leq x) (x \leq 1), R150 \rightarrow R250; R170 \rightarrow R260; R40 \rightarrow A; R50 \rightarrow B; \\ R60 \rightarrow 0 \vdash$$

36 :

$$(R160R120-R110R180)/(R80R160-R140R100) \rightarrow Y \vdash$$

37 :

$$\text{IF } (1/3 \leq Y) (Y \leq 1), Y \rightarrow R200, R50 \rightarrow R190, R80 \rightarrow R210, \\ R100 \rightarrow R220, R120 \rightarrow R230 \vdash$$

38 :

$$\text{IF } (1/3 \leq Y) (Y \leq 1), R140 \rightarrow R240, R160 \rightarrow R250, R180 \rightarrow R260, \\ R45 \rightarrow A, R55 \rightarrow B, R65 \rightarrow C \vdash$$

39 :

$$(R210R260-R240R250)/(R210R250-R240R220) \rightarrow R400 \vdash$$

40 :

$$1/9 + 33/16 + 0/18 + 1100/200 + (3/8 - 0/6 - 500/48)R200 \rightarrow S \vdash$$

41 :

$$3 + 3/16m(B + 33/2)R400 \rightarrow Y \vdash$$

42 :

$$(1/8m(33 - .500)R200 + 1/16m(B + .500)(R400 + 1))/Y \rightarrow Z \vdash$$

43 :

$$\text{IF } .01 > \text{ABS}(Z - R4), R19 + 1 \rightarrow R19 \vdash$$

44 :

IF ABS (X-R4) > .001, GOTO "INCREMENT" ↴

45 :

"PRINT" ; (3R200-1)/2 → R410, (3R400-3R200+3)/8 → R420 ↴

46 :

R400/2, 5FID 9.6, 2FID 12.6, 3FID 12.6; TIP R190, R10, A, B, C,  
R200, R400, X, R410, R420 ↴

47 :

TIP /, 2I, 9FID 8.4; TIP R1, R2, R4, R5, R18, R17, R3, R1/R3, R2/R3 ↴

48 :

GTO "READY" ↴

49 :

"END", END ↴